

Caustics

USING PHOTON MAPS

CS500 RAY TRACING

BORJA PORTUGAL MARTIN

Caustics using Photon maps

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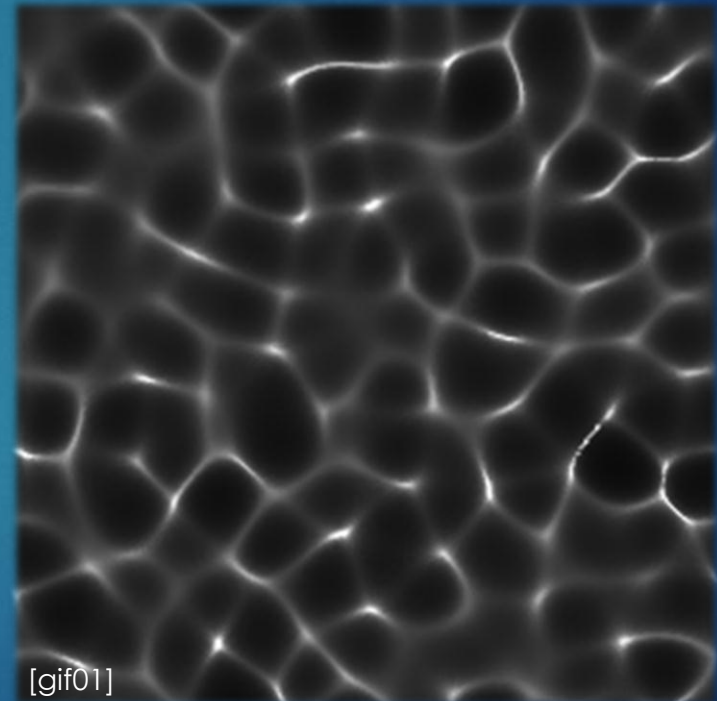
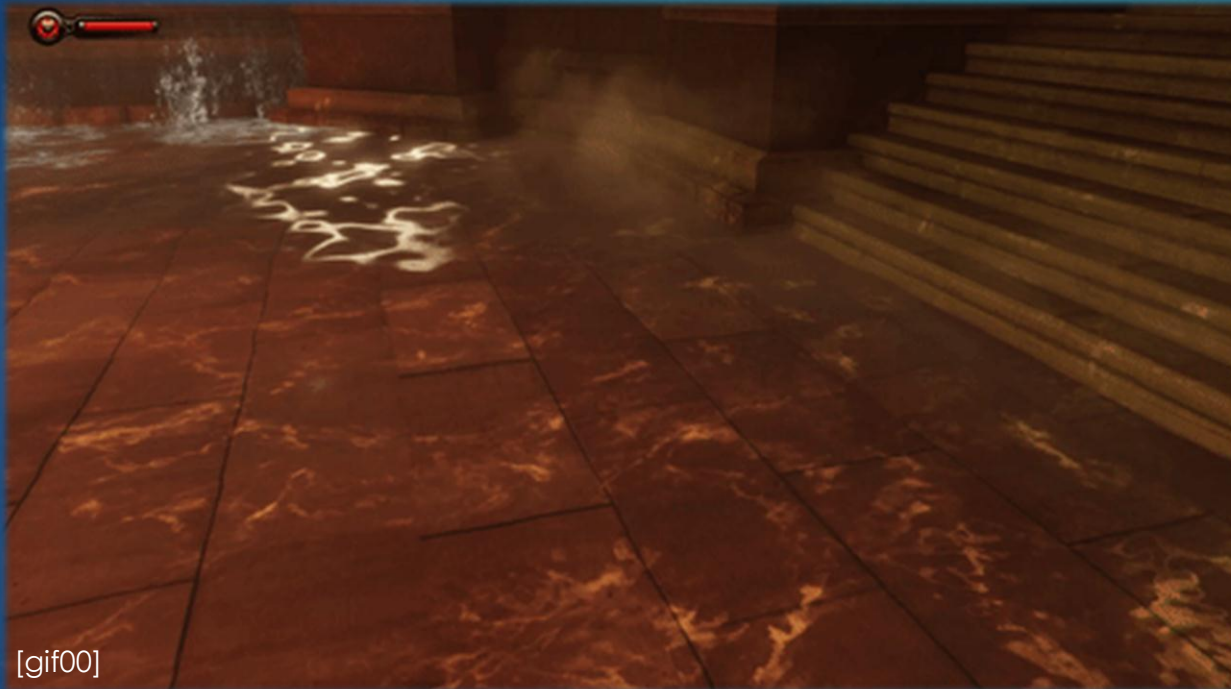
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Motivation

Motivation

Caustics in Video Games

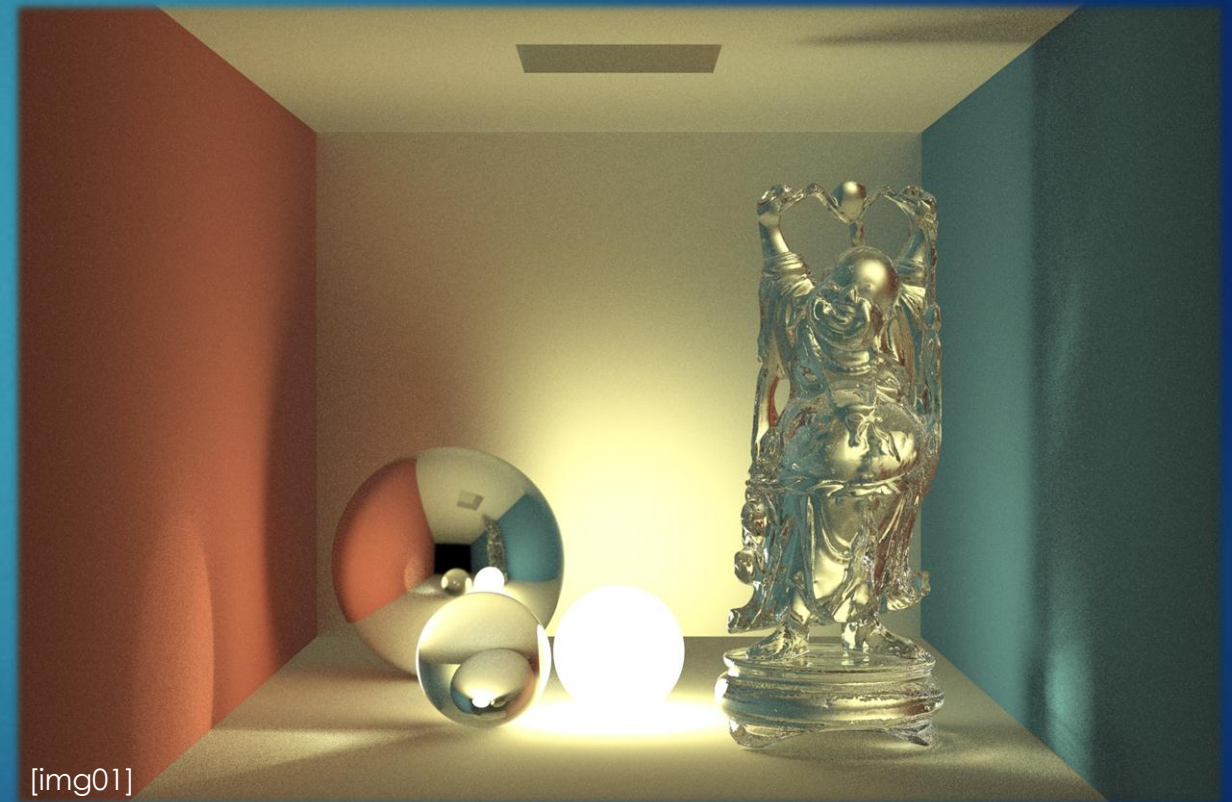
- Real time applications fake caustics



Motivation

Ray traced caustics

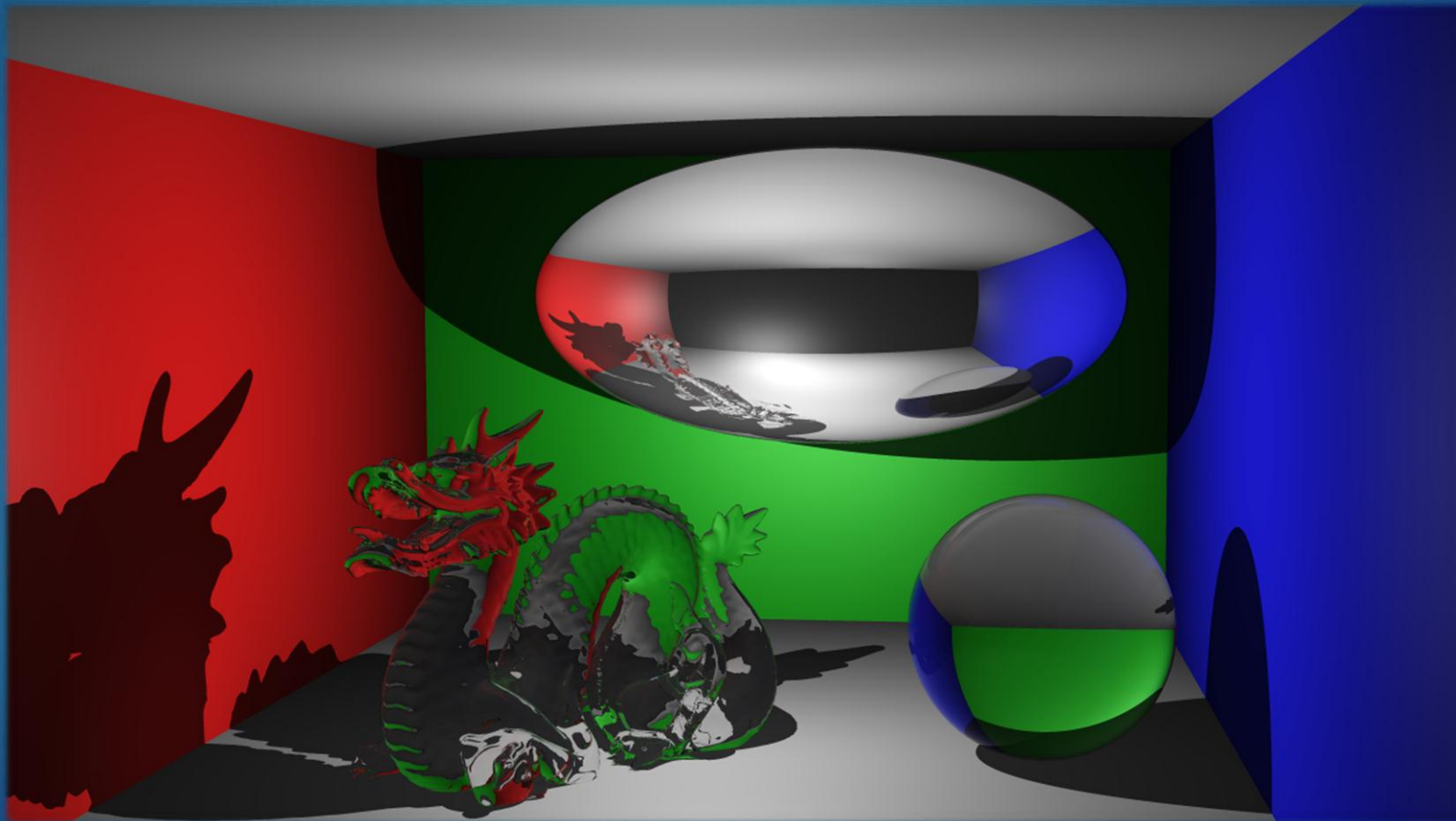
- Ray tracing is done offline, we can use all the computational power



Caustics

Motivation

- Glass in ray traced images without caustics do not seem correct



Approach

Approach

How can we do it?

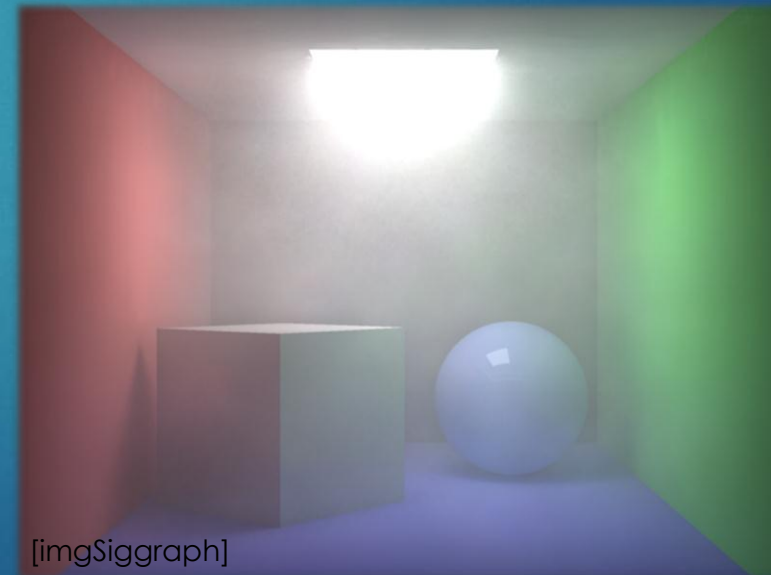
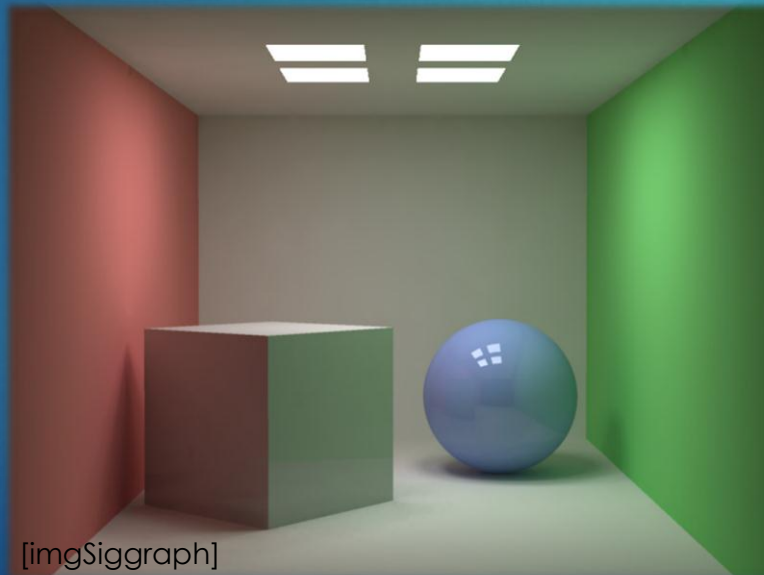
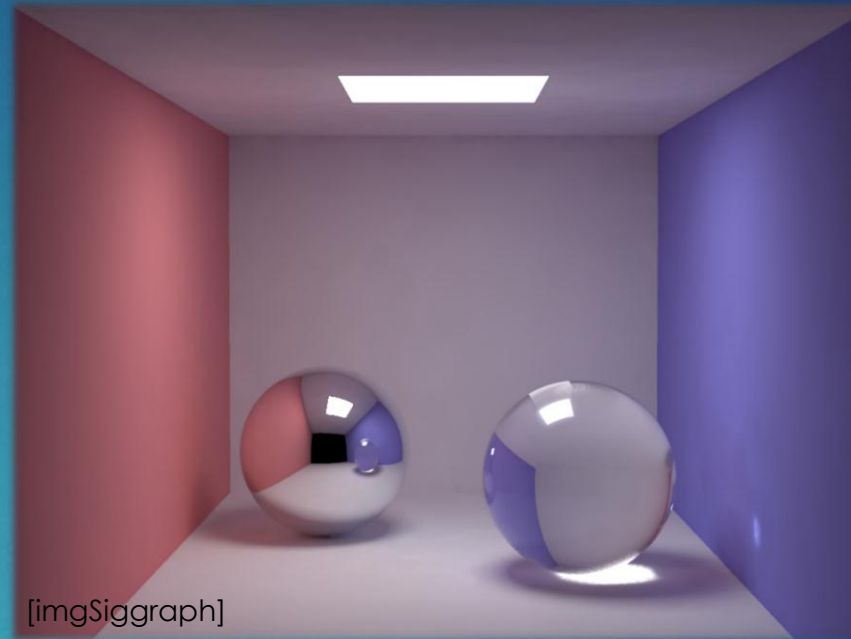
- ▶ We want to simulate what light does
 - ▶ Cast rays from the light source until we reach the camera (too expensive)
- ▶ Possible approaches:
 - ▶ Monte Carlo integration
 - ▶ Photon mapping: similar, but faster, approach to Monte Carlo

Photon maps

Photon maps

What are they used for?

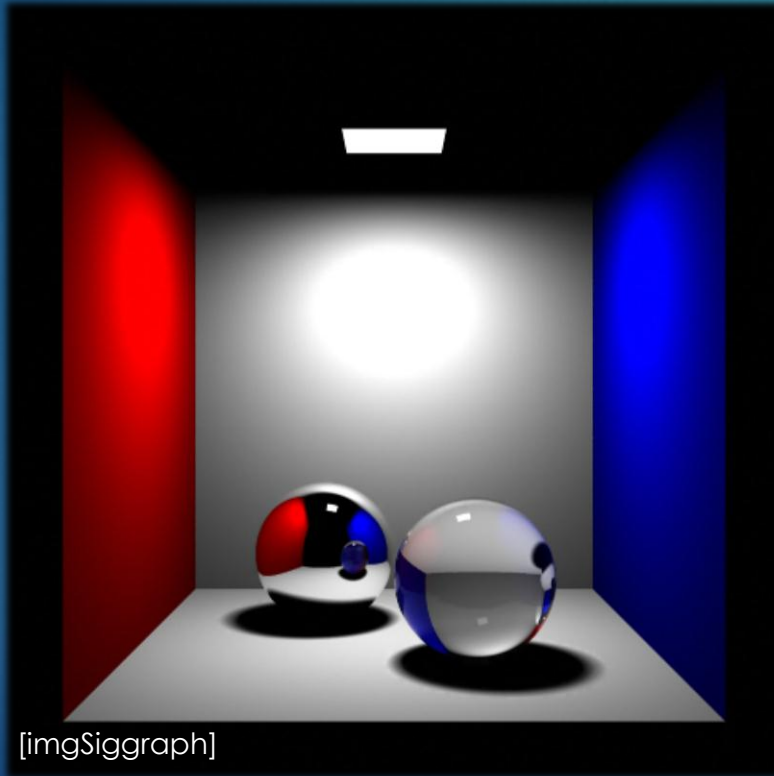
- ▶ Caustics
- ▶ Global illumination
- ▶ Participating media



Photon maps

What are they?

- ▶ Collection of photons (light rays that reached a diffuse surface)
- ▶ 3D (its name made me, at first, think they were 2D)



Photon maps

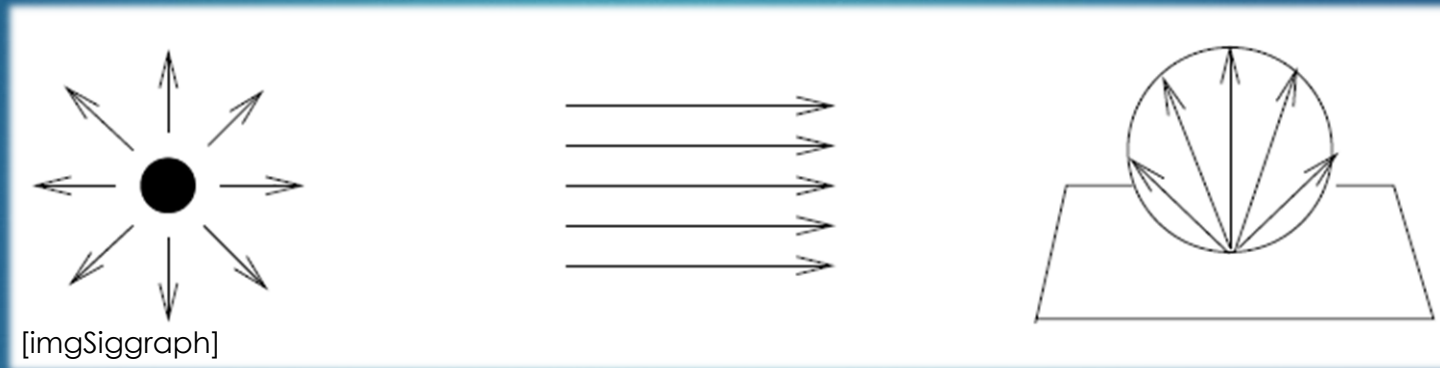
How are they generated?

1. Emit photons from the light sources
2. Trace photons until they reach a diffuse surface
3. Store them in a KD-Tree for fast access

Photon maps

Photon emission

- ▶ Photons are emitted from each light source
- ▶ Direction depends on the light type
 - ▶ Emission directions for point light, directional light and area light respectively



Photon maps

Photon emission

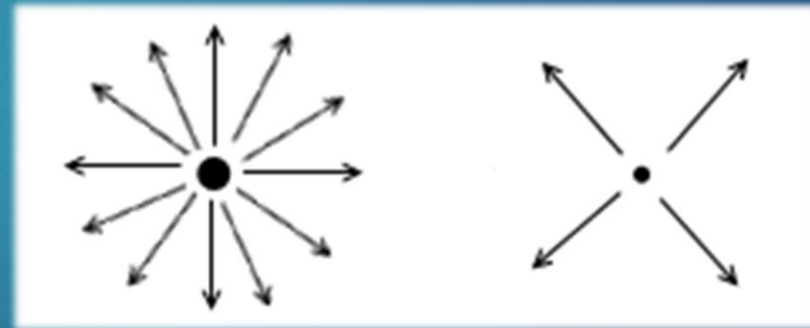
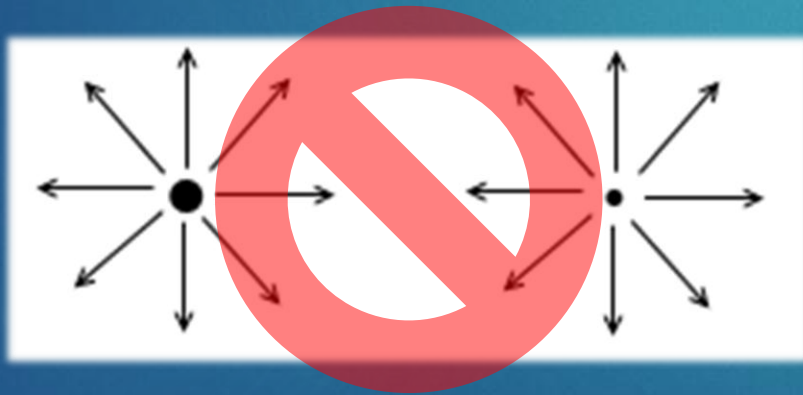
- ▶ Power of the photon
 - ▶ Information about the light source that emitted it
- ▶ Formula:
 - ▶ P_{photon} Power of each photon
 - ▶ P_{light} Power of the light
 - ▶ n_e Number of photons the light will emit

$$P_{\text{photon}} = \frac{P_{\text{light}}}{n_e}$$

Photon maps

Photon emission – Multiple lights

- ▶ We don't emit the same number of photons per light
- ▶ Lights with more intensity will emit more photons
 - ▶ Number of photons in the scene remains constant
 - ▶ Photons will have similar power
 - ▶ Makes the radiance estimate better



Photon maps

Photon emission – Multiple lights

	Light A	Light B	Total
Power	9	1	10
Contribution	90%	10%	100%
Number of photons	100	100	200
Photon power	$9/100 = 0.09$	$1/100 = 0.01$	10

	Light A	Light B	Total
Power	9	1	10
Contribution	90%	10%	100%
Number of photons	90	10	100
Photon power	$9/90 = 0.1$	$1/10 = 0.1$	10

Photon maps

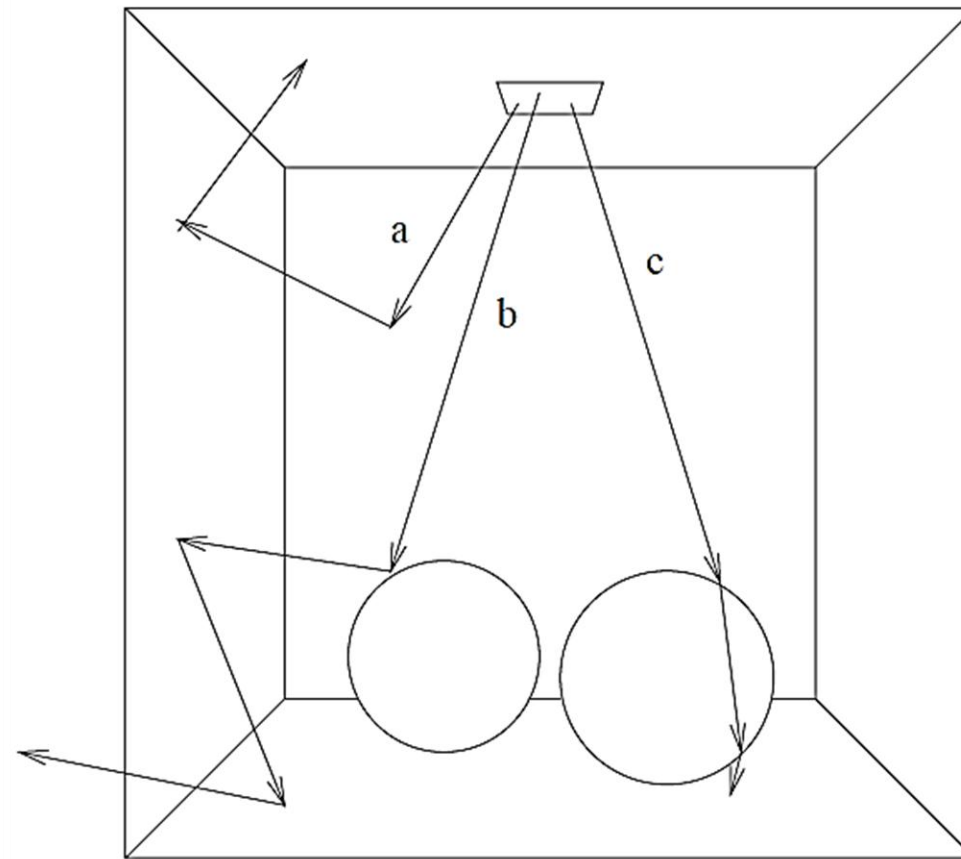
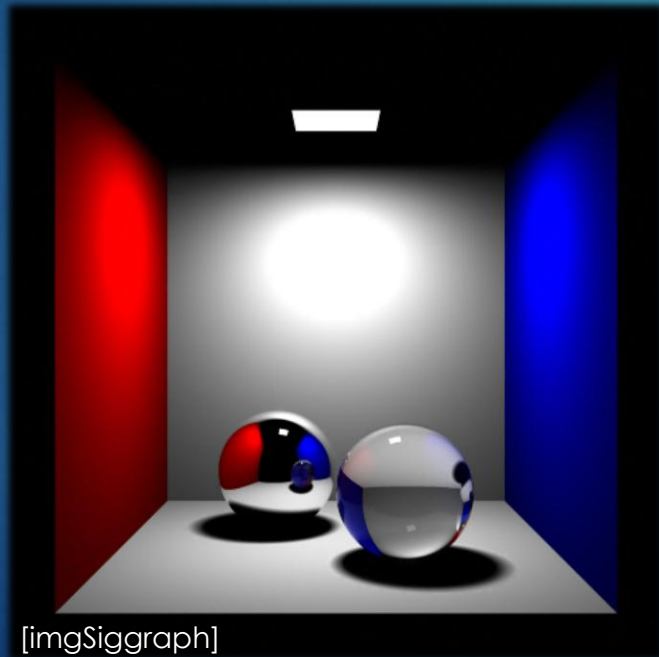
Photon tracing

- ▶ Each time we hit a surface we would need to generate 2 photons
 - ▶ Diffuse reflection
 - ▶ Specular reflection
- ▶ The 8th bounce would generate $2^8 = 256$ photons (this is bad)
 - ▶ A lot of memory needed
 - ▶ Most photons will have very low power
- ▶ Solution: Russian roulette
 - ▶ Probabilistic approach

Photon maps

Photon tracing – Russian roulette

- ▶ Photon path examples:
 - ▶ a: x2 diffuse -> absorption
 - ▶ b: specular -> x2 diffuse
 - ▶ c: x2 specular -> absorption



[imgSiggraph]

Photon maps

Photon tracing – Russian roulette

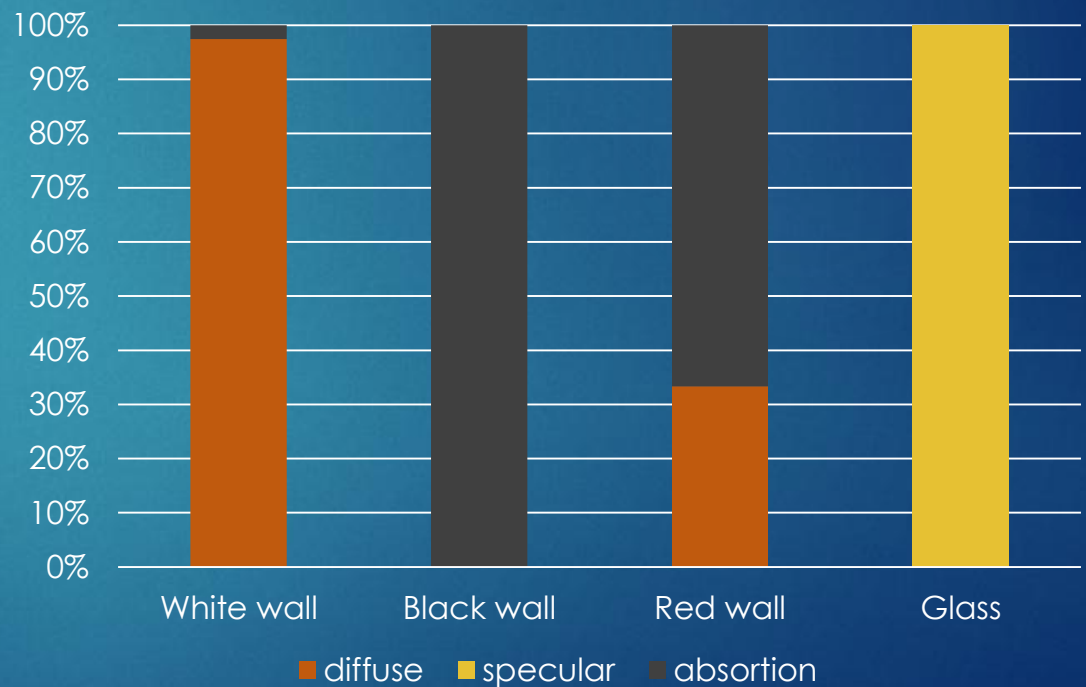
- ▶ Coefficients to determine the action of the photon

- ▶ D Diffuse reflection coefficient
- ▶ S Specular reflection coefficient
- ▶ $D \geq 0, S \geq 0, D + S \leq 1$

- ▶ Take random x where $x \in [0, 1]$

- ▶ $x \in [0, D] \rightarrow \text{diffuse reflection}$
- ▶ $x \in (D, D + S] \rightarrow \text{specular reflection}$
- ▶ $x \in (D + S, 1] \rightarrow \text{absorption}$

Example materials



Photon maps

Photon tracing – Russian roulette

- Compute coefficients out of RGB coefficients

$$P_r = \max(\underline{d_r + s_r}, \underline{d_g + s_g}, \underline{d_b + s_b})$$

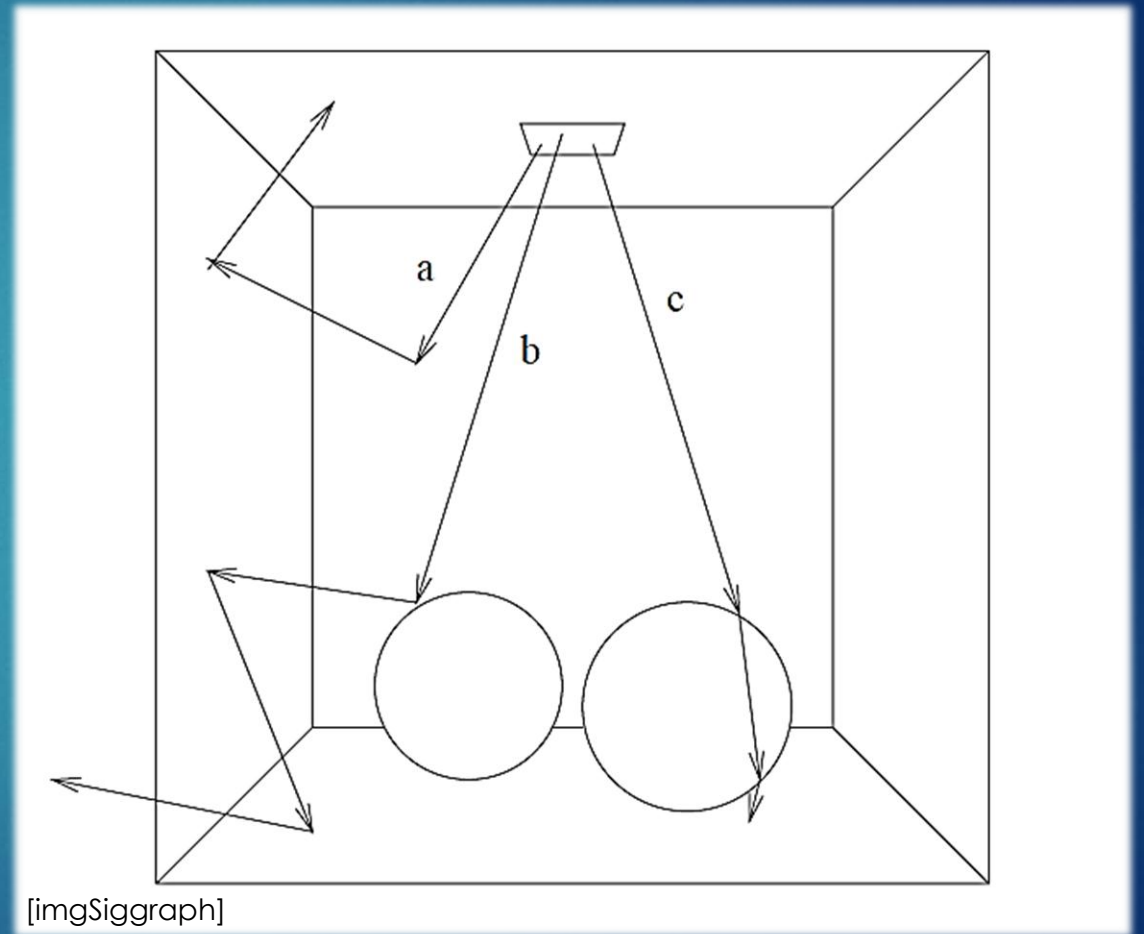
$$P_D = \frac{d_r + d_g + d_b}{d_r + d_g + d_b + s_r + s_g + s_b} P_r$$

$$P_S = \frac{s_r + s_g + s_b}{d_r + d_g + d_b + s_r + s_g + s_b} P_r = P_r - P_D$$

Photon maps

Photon tracing – Russian roulette

- ▶ Applying P_D and P_S
 - ▶ $x \in [0, P_D] \rightarrow$ diffuse reflection
 - ▶ $x \in (P_D, P_D + P_S] \rightarrow$ *specular reflection*
 - ▶ $x \in (P_D + P_S, 1] \rightarrow$ *absortion*



Photon maps

Photon tracing – Russian roulette (Summary)

► Pros:

- Reduces number of photon emission
 - Less computation & storage required
- Keeps photon powers similar → Better radiance estimate

► Cons:

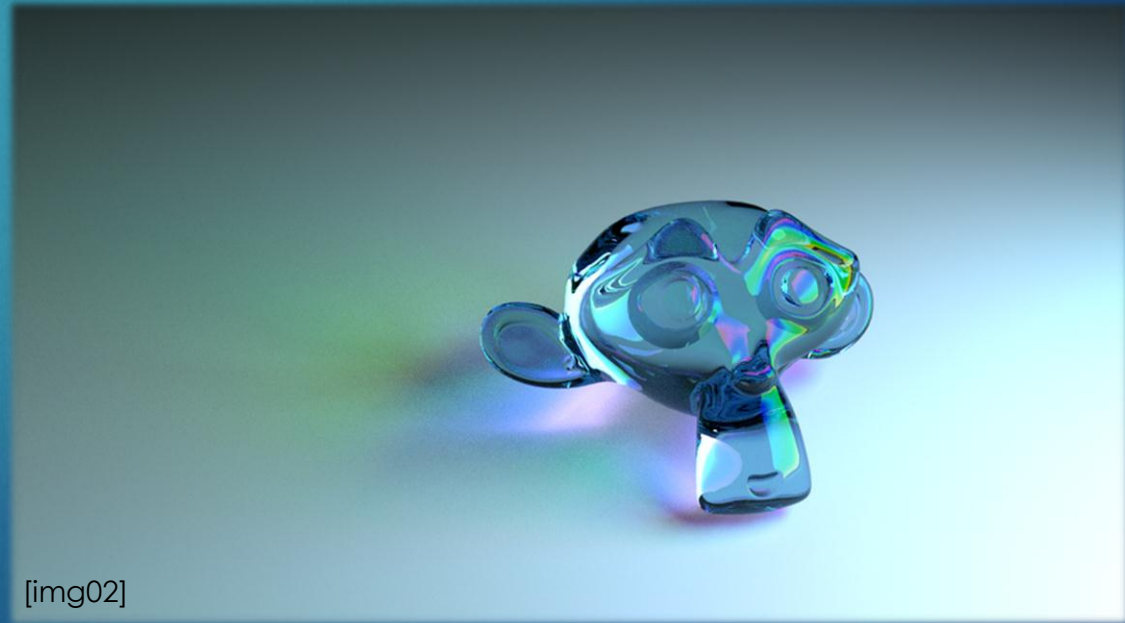
- Increases variance on the solution, we need to emit a lot of photons
 - Not as many as without using Russian roulette

Photon maps

Photon tracing

- ▶ When a photon hits a surface we need to update its power
 - ▶ P_{inc} Power of the incident photon
 - ▶ P_{refl} Power of the reflected photon
 - ▶ S Specular color of the surface (if specular reflection happens)

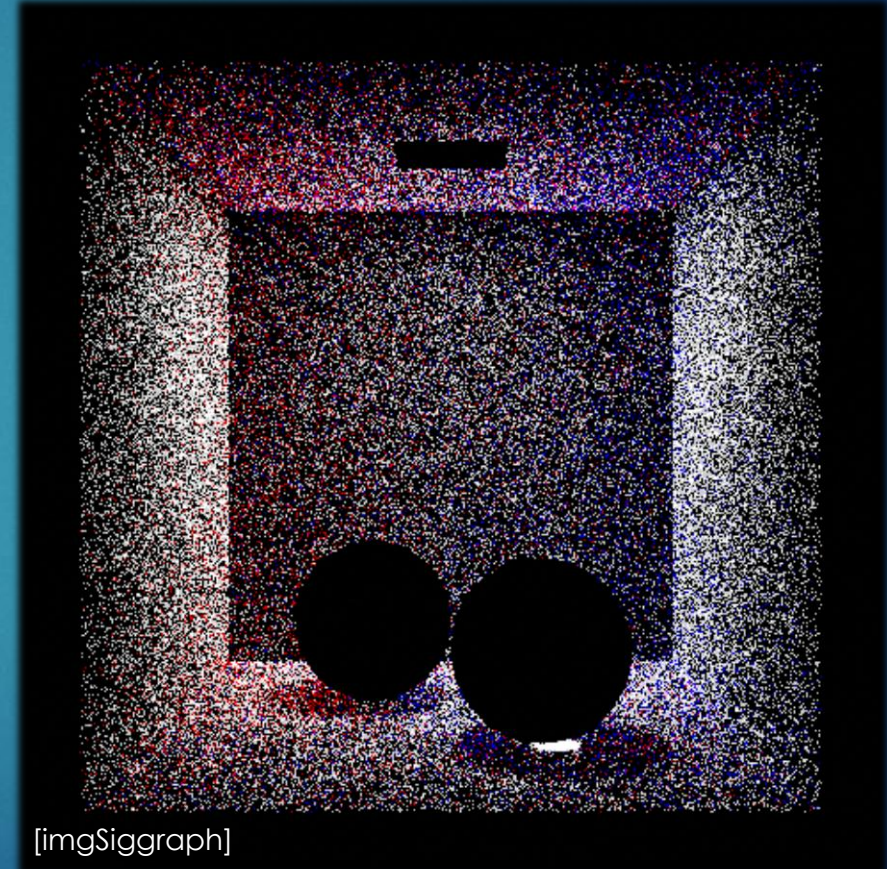
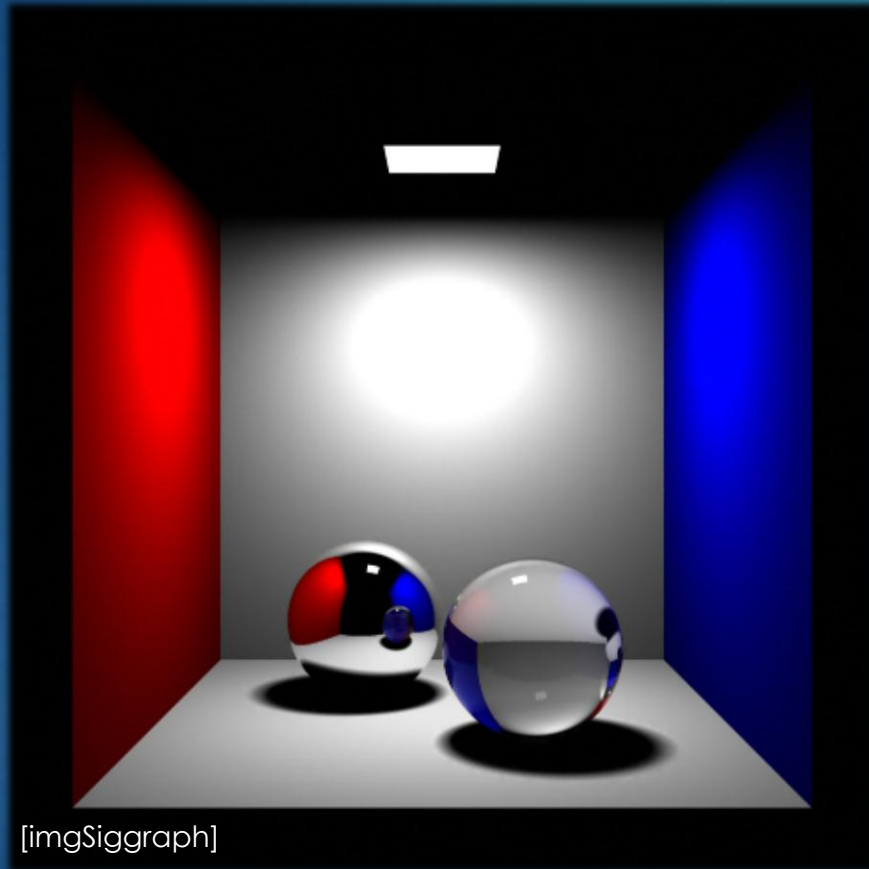
$$P_{refl} = \frac{P_{inc} S}{P_s}$$



[img02]

Photon maps

Photon tracing



Photon maps

Photon storing – The photon

```
struct photon
{
    float x, y, z;           // position
    float r, g, b;           // power
    float dx, dy, dz;        // incident direction
};    // 36 bytes
```

Photon maps

Photon storing – The photon

- In case memory is a concern, compressed version

```
struct photon
{
    float x, y, z;    // position
    char p[4];        // power packed as 4 chars (Ward's RGBE)
    char phi, theta;  // compressed incident direction
                     // (spherical coordinates)
    short flag;        // flag used in kd-tree
};    // 20 bytes
```

Photon maps

Photon storing – The photon

- ▶ Ward's RGBE packing
 - ▶ Same principle of mantissa and exponent in floating point values
 - ▶ Normalize RGB floats to chars, exponent gives us more precision
 - ▶ $RGB \rightarrow [0, 255]$ red, green, blue values
 - ▶ $E \rightarrow [0, 255]$ Exponent

Photon maps

Photon storing – The photon

► Incident direction packing

► *2 chars → 16 bits → $2^{16} = 65536$ possible directions*

$$phi = 255 * \frac{atan2(dy, dx) + \pi}{2\pi}$$

$$theta = 255 * \frac{acos(dx)}{\pi}$$

$$[-\pi, \pi] \rightarrow [0, 2\pi] \rightarrow [0, 1] \rightarrow [0, 255]$$

$$[0, \pi] \rightarrow [0, 1] \rightarrow [0, 255]$$

Photon maps

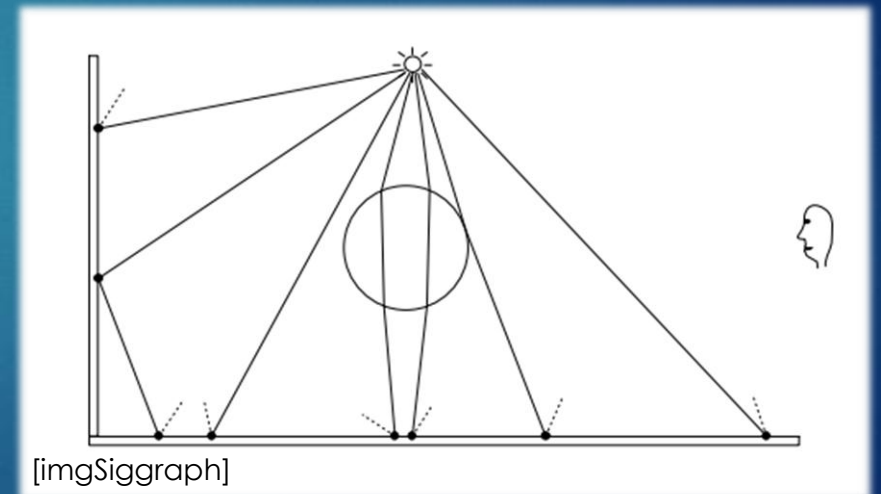
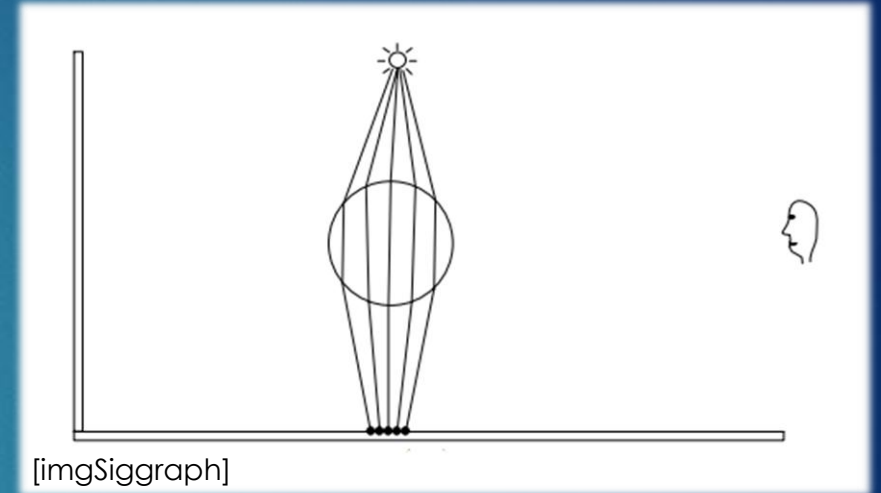
Photon storing – KD-tree

- ▶ Photons are stored when they hit diffuse surfaces
- ▶ Use a KD-Tree
 - ▶ $O(\log N)$
 - ▶ Make sure is well balanced
 - ▶ Use an array to represent it

Photon maps

Photon storing – Three maps

- ▶ Photon map types:
 - ▶ Caustics photon map → Caustics
 - ▶ Photon went at least through an specular reflection
 - ▶ Global photon map → Global illumination
 - ▶ Photons that hit a diffuse surface
 - ▶ Volume photon map → Indirect illumination
 - ▶ Indirect illumination of a participating medium



Photon maps

Summary

- ▶ Emit photons from all light sources
- ▶ Let the photons bounce through the scene
 - ▶ Use Russian roulette to determine action
 - ▶ Diffuse reflection, specular reflection or absorption
- ▶ Store the photons in the corresponding photon maps

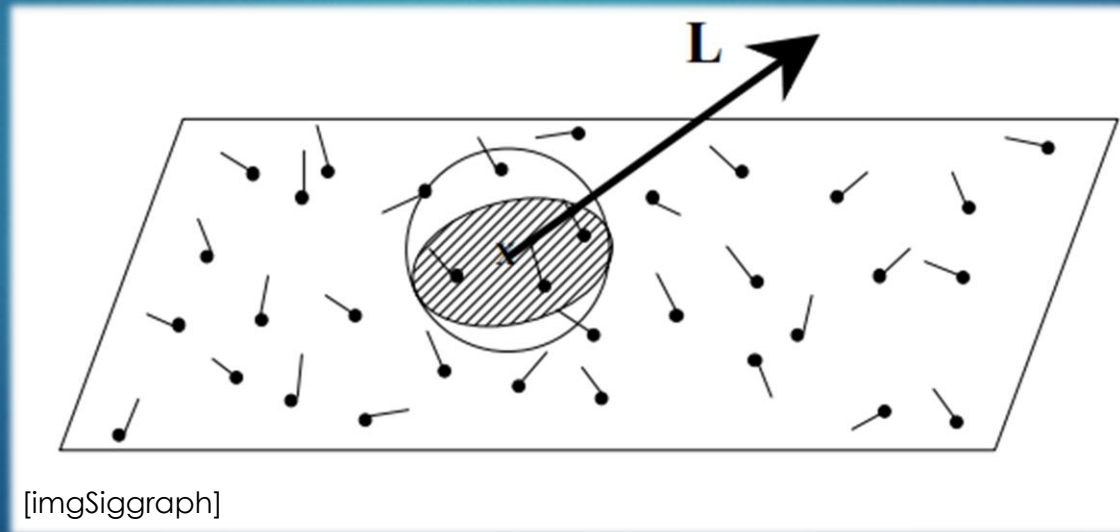
Rendering

Rendering

- ▶ Photon mapping is a 2 pass render technique
 1. Generate photon maps
 2. Use generated photon maps to get the radiance estimation on the surface

Rendering

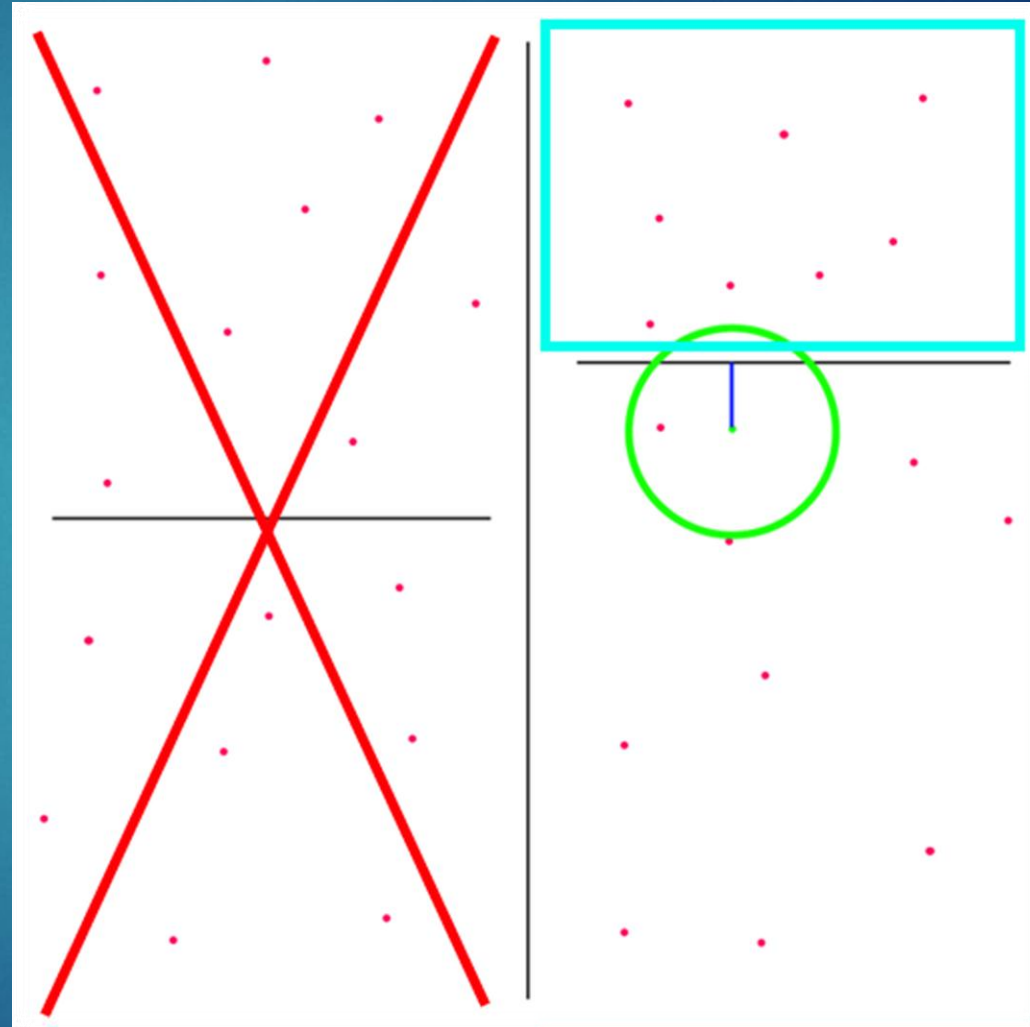
- ▶ Use the generated photon maps to get the radiance estimation
 - ▶ Caustics photon map
 - ▶ Global photon map
 - ▶ Volume photon map
- ▶ Get nearest photons in the surface → KD-Tree traversal



Rendering

KD-tree traversal

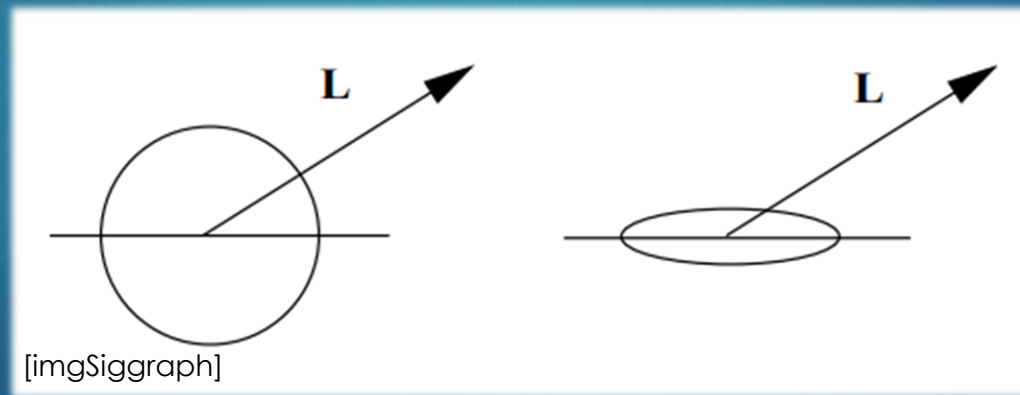
1. Check plane side
2. Traverse child node
3. Distance to plane $<$ Threshold
 1. Traverse other child



Rendering

Sphere VS Disk

- ▶ Sphere
 - ▶ Fast to locate photons, just need squared distance
 - ▶ Can give wrong approximations on corners
- ▶ Disk
 - ▶ Slower
 - ▶ More accurate, takes surface into account



Rendering

Radiance estimate – Formula

► Outgoing = Emitted + Reflected

► $L_o \rightarrow$ Outgoing radiance

► $L_e \rightarrow$ Emitted radiance

► $L_r \rightarrow$ Reflected radiance

► $x \rightarrow$ Surface position

► $\vec{w} \rightarrow$ Direction (Surface to camera)

$$L_o(x, \vec{w}) = L_e(x, \vec{w}) + L_r(x, \vec{w})$$

Rendering

Radiance estimate – Formula

- ▶ Reflected radiance is computed by integrating the incoming radiance
 - ▶ $f_r(x, \vec{w}', \vec{w}) \rightarrow$ *Illumination function (in my case phong)*
 - ▶ $L_i(x, \vec{w}')$ \rightarrow *Incoming radiance*
 - ▶ $\Omega_x \rightarrow$ hemi – sphere of incoming directions

$$L_r(x, \vec{w}) = \int_{\Omega_x} f_r(x, \vec{w}', \vec{w}) L_i(x, \vec{w}') |\vec{n}_x \cdot \vec{w}'| dw'_i$$

Rendering

Radiance estimate – Formula

- ▶ Apply relation between the radiance and the flux
- ▶ The flux is represented by photons in the photon map
 - ▶ $N \rightarrow$ number of photons near x

$$L_r(x, \vec{w}) = \frac{1}{\pi r^2} \sum_{p=1}^N f_r(x, \vec{w}_p', \vec{w}) \Delta\Phi_p(x, \vec{w}_p)$$

Rendering

Radiance estimate – Formula

- ▶ Total incoming radiance $L_i(x, \vec{w})$ is the sum of all radiances
 - ▶ $L_{i,l}(x, \vec{w}) \rightarrow$ *Direct illumination*
 - ▶ $L_{i,c}(x, \vec{w}) \rightarrow$ *Caustics*
 - ▶ $L_{i,d}(x, \vec{w}) \rightarrow$ *Indirect illumination*

$$L_i(x, \vec{w}) = L_{i,l}(x, \vec{w}) + L_{i,c}(x, \vec{w}) + L_{i,d}(x, \vec{w})$$

Rendering

Radiance estimate – Formula

$$L_r(x, \vec{w}) = \int_{\Omega_x} f_r(x, \vec{w}', \vec{w}) L_i(x, \vec{w}') |\vec{n}_x \cdot \vec{w}'| dw'_i$$

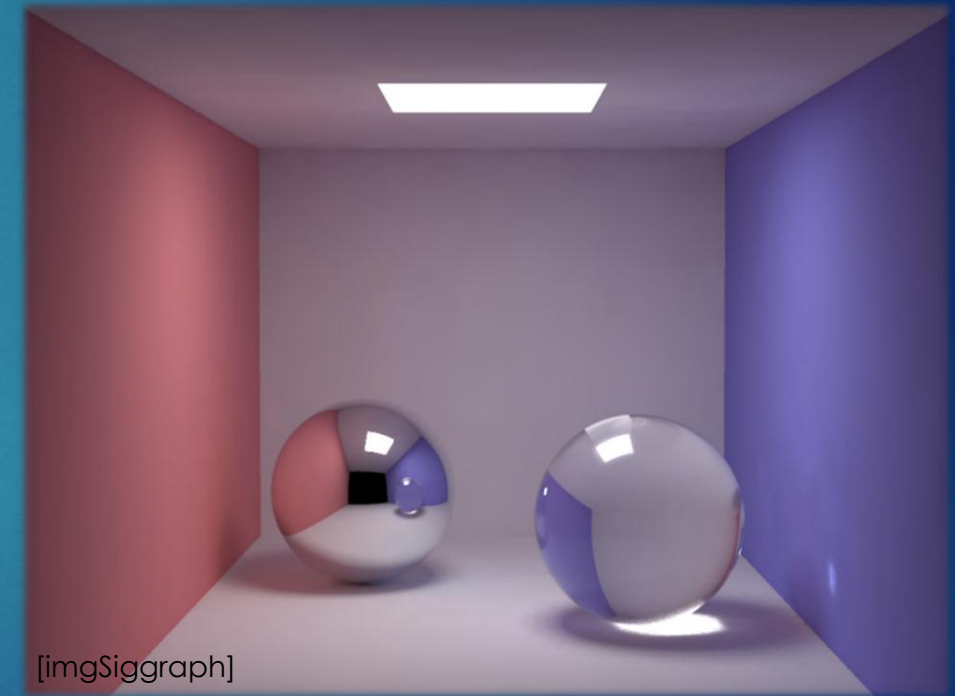
$$\frac{1}{\pi r^2} \sum_{p=1}^N f_r(x, \vec{w}_p', \vec{w}) \Delta\Phi_p(x, \vec{w}_p)$$

$$L_i(x, \vec{w}) = L_{i,l}(x, \vec{w}) + L_{i,c}(x, \vec{w}) + L_{i,d}(x, \vec{w})$$

Rendering

Radiance estimate - Filtering

- ▶ We average the flux in an area
- ▶ Special problem with Caustics
 - ▶ We want to preserve their sharp edges
- ▶ We use filtering to get better results
 - ▶ Increase weight of photons near the point of interest



Rendering

Radiance estimate - Filtering

► Gaussian filter

► $d_p \rightarrow$ Distance from x to the photon

► $\alpha = 0.918$

► $\beta = 1.953$

$$w_{pg} = \alpha \left[1 - \frac{1 - e^{-\beta \frac{d_p^2}{2r^2}}}{1 - e^{-\beta}} \right]$$

$$L_r(x, \vec{w}) = \frac{1}{\pi r^2} \sum_{p=1}^N f_r(x, \vec{w}_p', \vec{w}) \Delta\Phi_p(x, \vec{w}_p) w_{pg}$$

Summary

Summary

- ▶ Photon mapping is a 2 pass rendering technique
 1. Generate photon maps
 - ▶ Use Russian roulette (reflect or absorb)
 2. Render scene
 - ▶ Use photon maps to get the radiance average
 - ▶ Apply filtering in case of caustics
 - ▶ Maintain sharp edges

Conclusion

Conclusion

Why photon mapping?

- ▶ Photon mapping is less expensive than Monte Carlo integration
 - ▶ Russian roulette
 - ▶ Probabilistic approach to reduce the number of photons
 - ▶ Number of lights does not affect photon number
 - ▶ While rendering just need to find the nearest photons
 - ▶ KD-Tree $\rightarrow O(\log N)$

Credits

- ▶ All the formulas and theoretical references of this presentation are from “Siggraph 2000 - A Practical Guide to Global Illumination using Photon Maps” (Order and arrangement of contents may not be the same)
 - ▶ <https://graphics.stanford.edu/courses/cs348b-00/course8.pdf>
- ▶ [imgSiggraph]: image taken from the document above
- ▶ [gif00]: Gif I created using giphy.com of the Bioshock Infinite game
 - ▶ <https://giphy.com/gifs/bioshock-infinite-zrqsuyczat4U8/>
- ▶ [gif01]: <https://opengameart.org/content/water-caustics-effect-small>
- ▶ [img00]: <https://commons.wikimedia.org/wiki/File:Caustics.jpg>
- ▶ [img01]: <https://www.flickr.com/photos/snogglethorpe/2612616268>
- ▶ [img02]: <http://therealrichard.deviantart.com/art/Caustics-and-Coloured-Emission-277601210>



Thanks for listening!

Questions?